	COMPETENCY MAPPING
STCW Table:	Table A – II / 1
Title:	Specification of minimum standard of competence for officers in charge of a navigational watch on ships of 500 gross tonnage or more.
Guidance Notes	(Scoring)
Terms	Description
Reward	Earned points, an integer within the range of 0 to 100. The default value is 0.
Penalty	Penalty points, an integer within the range of 100 to 0. The default value is 100.
Single	A rule is triggered in the scenario only once: the first time the conditions occur.
Circular	A rule is triggered every time the conditions occur.
Time	Time dependency ruling
Weight	Multiplier is used to determine trainee's level of competency
Levels of Simula	tion
Familiarization	Familiar with the equipment, layout procedures, and routine task.
Operational	The task relates to the inputs and outputs and their relationship and has to do with the performance of a function.
Functional	The task relates to the functions or activities performed by the system without reference to which of the elements of the system perform those functions.
Management	Relates to the management of the combination of systems to perform a given job.
Communication	Relates to effective communication between human resources to report, get feedback, or to execute a task.
Emergency	Task performed in circumstances where there is variation or deviation from an expected scenario or situation.
Crisis	Task performed when the emergency has developed into a crisis.



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MARITIME INDUSTRY AUTHORITY

COMPETENCY MAPPING

Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
FUNTION 1	NAVIGATION AT THE	OPERATIONAL LEVEL			·		
Plan and conduct a passage and determine position	C1.1 Celestial Navigation .1 Ability to use celestial bodies to determine the ship's position	At the end of the assessment, the candidate will be able to use celestial bodies to determine the ship's position.	Determine position using celestial bodies	 1.Adjust any of the following sextant errors: a. Perpendicularity; b. Side error; c. Parallelism; and d. Collimation error. 2. Given a true altitude and observed sextant altitude of the sun and its azimuth, plot the Line of Position (LOP) using intercept method. 3. Given true altitudes and observed sextant altitudes of at least three (3) stars and its azimuth, plot the Line of Position (LOP) using intercept method. 	Rubrics	N/A	N/A



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	C1.2 Terrestrial and coastal navigation Ability to determine the ship's position by use of: .1 landmarks .2 aids to navigation, including lighthouses, beacons and buoys .3 dead reckoning, taking into account winds, tides, currents and estimated speed	At the end of the assessment, the candidate will be able to determine and plot the bearings of two charted objects	Appropriatene ss and reliability of the method used in fixing ship's position at regular intervals. Appropriatene ss of the primary method of fixing the ship's position to the prevailing circumstances and conditions	Use the terrestrial or coastal landmark in fixing ship's position on the following: 1. Determine the bearings of two charted objects and plot them; 2. Position is within±0.10 nm; 3. Crossing angles of bearing is not less than 30° nor more than 160° between bearings; and 4. Use of the largest scale charts suitable for the waters being transited	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge
	C1.3 Thorough knowledge of and ability to use nautical charts, and publications, such	At the end of the assessment, the candidate will be able to identify the charts needed for the	Suitability and correctness of the largest scale charts selected for the area of navigation and	Satisfies the following: a. Correctly identifies and records the names and numbers of the charts;	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge



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	as sailing directions, tide tables, notices to mariners, radio navigational warnings and ships' routeing information	voyage	publications in accordance with the latest information available Correctness and relevance of the information obtained from nautical charts and publications and accurateness in identifying potential navigational hazards	b. Selects the charts with the largest scales appropriate for the area being transited; and			
	C1.4 Electronic systems of position fixing and navigation .1 ability to determine the ship's position by use of electronic navigational aids	At the end of the assessment, the candidate will be able to determine ship's position using GPS, RADAR/ARPA	Application of acceptable instruments/syst em error to determine ship's position within the limit	Initialize the system; and Determine the accuracy of the position using the following: a. GPS b. RADAR/ARPA, c. ECDIS	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge
	C1.5	At the end of the	Compliance of	Ensures the following:	Reward/	Operational/	Full Mission



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	Echo Sounders .1 ability to operate the equipment and apply the information correctly	assessment, the candidate will be able to turn on, tests, and operates the echo sounder	the performance checks to navigation systems with manufacturer's recommendatio ns and good navigational practice	 Turns the system on; Tests the echo sounder in accordance with manufacturer's recommendations; Notes the correct UTC on the echo sounder; Ensures that the scale selected is the lowest appropriate for the vessel's draft and the depth of water of the area of transit; and Adjusts the sensitivity to obtain proper depth reading on the display 	Penalty	Functional	Stimulator and Mini Bridge
	C1.6 Compass – magnetic and gyro .1 Knowledge of the principles of magnetic and gyro compasses .2 Ability to determine errors	At the end of the assessment, the candidate must be able to determine variation, deviation, magnetic compass error and gyro compass error	Determination of error in magnetic and gyro compasses are correctly applied to courses and bearings	Describe variation and deviation on the following: Determines errors of the magnetic and gyro compasses using terrestrial such as: 1. Compares the magnetic compass heading to the corrected gyro heading (corrected for a known gyro error); 2. Determines the magnetic compass error to within ± 1.0°	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge



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				 Compares the magnetic compass heading to the charted range bearing; Determines variation from the chart; Determines the magnetic compass deviation to with-in ± 1.0° Correctly records it in the compass record book and the ship's log. 			
	C1.7 Steering Control System .1 Knowledge of steering control systems, operational procedures and change-over from manual to automatic control and vice versa. Adjustment of controls for optimum performance	At the end of the assessment, the candidate must be able to conducts the pre-departure tests of the vessel's steering gear	Suitability of the selected steering mode for the prevailing weather, sea, traffic conditions and intended maneuvers	 a. Turns on the steering b. control system; c. Aligns the steering gyrorepeater with the master gyro compass; d. Tests the controls for switching pumps and motors between the port and starboard steering systems after the required warm-up period Tests the steering systems as follows: 1) When the control is switched to hand steering, the rudder is tested throughout its full range of 	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge



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				 motion: and When the control is switched to non fol-low-up, the rudder is tested throughout its full range of motion; Switching over of steering mode from auto/manual vice ver-sa; Set both steering mo-tor in operation; Set the weather control in accordance with the manufacturer's recommendations for the prevailing sea condi-tions for the area transited or simulated; and Set the rate of turn control (if fitted) in ac-cordance with the standing orders. 			
	C1.8 Meteorology .1 Ability to use and interpret information obtained from ship borne meteorological		the MARINA	f the candidate has suc Competency Assessm	-	•	



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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
C2	Maintain a safe navigational watch	instruments .2 Knowledge of the characteristics of the various weather system, reporting procedures and recording systems .3 Ability to apply the meteorological information available C2.1 Watchkeeping .1 Thorough knowledge of the content, application and intent of the International Regulations for Preventing Collisions at Sea 1972 as	At the end of the assessment, the candidate must be able to observe the principles and procedures in maintaining a safe navigational watch	Conformance and recognition of correct lights, shapes, and sound signals to the requirements contained in the COLREG 1972	Conform the following: 1. Correctly identifies the situation or position of 4 to 5 vessels that have different required shapes and sounds; and 2. Switching on the navigational lights and automatic fog signals	Rubrics	Operational/ Functional	Full Mission Stimulator and Mini Bridge



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Competence	amended .2 Thorough knowledge of the principles to be observed in keeping a navigational watch			Observes the principles and procedures in keeping a navigational watch such as: 1. Read the standing orders and night orders 2. Note the position of the next charted waypoint 3. Determine and compare the vessel's position, course, and speed. 4. Verify the identities of critical aids to navigation in sight.			
				 Determine tides and current as necessary. Check and properly tune the radar and/or ARPA. Check any targets displayed on the radar or ARPA. Check the heading by magnetic compass. (Compare gyro magnetic compass) Determine navigational hazards likely to be encountered during the 			



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				watch. 10. Determine possible effect of list, trim, water density and, squat on under-keel clearance 11. Identify vessels through observation of their required shapes 12. Identify vessels by hearing their required sound signals 13. Determines if risk of collision exists with approaching meeting, crossing, and overtaking vessels			
	.3 The use of routeing in accordance with the General Provisions on Ships' Routeing	At the end of the assessment, the candidate must be able to collect information to plan a safe and environmentally sound voyage plan, taking into account paragraph 2 of the annex to IMO Assembly Resolution A893 (21)	Development of voyage plan in accordance with the General Provisions on Ships' Routeing	Ensure that the following are taken into account when creating a voyage plan: 1. Up to date charts of proper scale and the latest notices to mariners 2. Up to date sailing directions 3. Up to date tide and current tables			



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				4. Weather information5. Weather routing services6. Port information			
	.4 The use of information from navigational equipment for maintaining a safe navigational watch	At the end of the assessment, the candidate must be able to use the information from navigational equipment for maintaining a safe navigational watch	Application of the International Regulations for Preventing Collisions at Sea, 1972 regarding frequency and extent of monitoring of traffic, the ship and environment to accepted principles and procedures	Applies the International Regulations for Preventing Collisions at Sea, 1972and maneuvers the vessel to avoid collision, if required such as: 1. Determine the aspect of the approaching vessel. 2. Identify the situation as a crossing situation. 3. Take positive action with ample time in accordance with the Steering and Sailing Rules to achieve a CPA of at least 1 .0 nm. 4. Make speed or course changes that are large enough to be readily apparent to another vessel observing visually or by radar	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge
	.5 Knowledge of blind pilotage techniques	At the end of the assessment the candidate must be able to recognize and	Clarity on the responsibility for the safety of navigation is	Recognizes the restricted visibility and takes appropriate action to navigate in restricted visibility in accordance with	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge



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 Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
on to navigate the sel	defined at all times including periods when the master is on the bridge and while under pilotage	 STCW Code Section A-VIII/2, Part 3, Paragraph 45 such as: Determines the restricted visibility; Notifies Master of restricted visibility; Switches to hand steering; Posts a proper lookout and turns the running lights on; Adjusts the vessel's speed in accordance with Rule 6; Sounds the required sound signals; Sets the radar and/or ARPA on the appropriate scale to scan at long range for other vessels; Plots all approaching targets on the radar or ARPA, if fit-ted; and Uses radar or ARPA, if fitted, to obtain early warning of risk of collision and to determine the speed and direction of relative motion. Keep navigational watch as per IMO Table of Watch Keeping Arrangement and the notation 			



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				on the chart where the presence of the Master and/ or pilot is required.			
	.6 The use of reporting in accordance with the General Principles for Ship Reporting Systems and with VTS procedures	At the end of the assessment the candidate must be able to establish and maintain communications with VTS	Maintenance of the proper records of the movements and activities relating to the navigation of the ship	 a) Keeps the records such as: Establishes communication with a VTS; b) Provides the initial information exchange as required by the VTS; c) Updates information during transit as required by the VTS; d) Closes communications with the VTS as the vessel departs the VTS jurisdiction 	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge
	C2.2 Bridge Resource Management Knowledge of bridge resource management principles, including: .1 allocation, assignment and prioritization of	At the end of the assessment the candidates must be able to manage available bridge resources	Allocation and assignment of tasks to other members of bridge team	Notifies the Master immediately on the following situation: 1. Vessel encounters or expects to encounter restricted visibility; 2. There is cause for concern because of vessel traffic density or			



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		resources .2 effective communication .3 assertiveness and leadership .4 obtaining and maintaining situational awareness .5 consideration of team experience			the movements of other ships; 3. Vessel will transit restricted waters with vessel traffic; or 4. Fatigued to the point that decision making is affected. The candidate assigns the bridge team duties, considering their background, experience and abilities to the following tasks: 1. Conning; 2. Look out; 3. Collision avoidance; 4. Navigation; 5. Communication; and 6. Administration			
C3	Use of radar and ARPA to maintain safety of navigation Note: Training and	Radar Navigation C3.1 Knowledge of the fundamentals of RADAR and Automatic RADAR Plotting Aids (ARPA)	examination in	the MARINA Knowledge	f the candidate has suc Competency Assessm of the fundamentals of	nent Syste	m under C	ompetence



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assessment in the use of ARPA is not required for those who serve exclusively on ships not fitted with ARPA. This limitation shall be reflected in the endorsement issued to the seafarer concerned	C3.2 Ability to operate and to interpret and analyze information obtained from RADAR, including the following: Performance, including: 1. factors affecting performance and accuracy 2. setting up and maintaining displays 3. detection of misinterpretation of information, false echoes, sea return, etc., RACONs and SARTs	At the end of the assessment the candidate must be able to operate and to interpret and analyze information obtained from radar and ARPA to maintain safety of navigation	Correctness of the setting up and adjustment of controls	 Execute within 3 minutes after the power is turned on the following: Switches the set from standby to transmit; Selects the appropriate scale; Adjusts the gain control so that targets and sea return appear; Adjusts the tune control (if the unit is not self-tuning); Adjust the brilliance control; Adjusts the sea clutter and rain clutter controls to suppress the rain and sea clutter without losing targets; Selects the north-up stabilized relative motion; and Recognize and correctly identifies RACON and SART 	Penalty/ Reward	Management/ Operational	Full Mission Stimulator and Mini Bridge



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	Use including: .1 range and bearing; course and speed of other ships; time and distance of other ships; effect of changes	At the end of the assessment the candidate must be able to use range and bearing; course and speed of other ships; time and distance of other ships; effect of changes	Timely decisions to amend course and or speed are in accordance with accepted navigation practice Adjustments made to the ship's course and speed maintain safety of navigation	Determines the range and bearing to an object Range is within ± 0.1 nm of the assessor's solution or ± 1% of the range scale in use; and Bearing is within ± 1 degree			
	.2 identification of critical echoes; detecting course and speed changes of other ships; effect of changes in own ship's course or speed or both	At the end of the assessment the candidate must be able to identify critical echoes; detect course and speed changes of other ships	Determination if risk of collision or danger of collision exists with all approaching vessels	Identifies all approaching vessels whose bearings do not change appreciably and vessel that have a CPA of less than 3nm The candidate makes all determination within 6 minutes of determining the initial range and bearing of each vessel			
	.3 application of the International Regulations for Preventing	At the end of the assessment the candidate must be able to apply the	Determination of the target vessel's relative motion by	determines the new course to steer to achieve a 2nm CPA; execute a turn to a			



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	Collisions at Sea, 1972, as amended	International Regulations for Preventing Collisions at Sea, 1972, as amended	changing own ship's course/speed reduction in accordance with the COLREGS	starboard; 3. achieves a CPA of not less than 1.5 nm or not more than 2.2 nm and 4. execute a speed reduction			
	.4 plotting techniques and relative and true motion concepts	At the end of the assessment the candidate must be able to plot techniques and relative and true motion concepts	Determination of the true course and speed of at least three target vessels	 construct a relative triangle by the use of maneuvering board or a transfer plotting sheet; solves for target vessel's true course and speed within 6 minutes; and determines the true course within ± 5 degrees and the true speed within ± 5 knots 			
	.5 parallel indexing	At the end of the assessment the candidate must be able to use parallel indexing techniques	Usage of parallel index line to continuously monitor and maintain the vessel on track	 Construct a parallel index line through the edge of the known hazard to navigation Monitors the vessel's movement by referring to the relative position of the parallel index relative to the land mass or other radar conspicuous target; and ensures the vessel drifts not more than 10% of the set distance towards the known hazard 			



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C3.3 Principal types of ARPA, their display characteristics, performance standards and the dangers of overreliance of ARPA		der Compete	f the candidate has sucence 3, KUP .3 – Ability d from ARPA.	•	•	
C3.4 Ability to operate and to interpret and analyze information obtained from ARPA including; .1 system performance and accuracy, tracking capabilities and limitations, and processing delays .2 use of operational warnings and system tests 3 methods of target acquisition and their limitations	At the end of the assessment the candidate must be able to use radar and ARPA to maintain safety of navigation	Usage of radar and ARPA control knobs to maintain safety of navigation	 Execute within 3 minutes the following: Turns the power on; Initializes the performance monitor; Notes error messages; Switches from standby to on; Selects the appropriate scale; Adjusts the gain control and sea return appear; Adjust the tune control Adjust the brilliance control Adjust the sea clutter and rain clutter control to suppress the rain and sea clutter without losing targets; Selects display north-up stabilized relative motion; Selects proper gyro course and speed input; and 	Penalty/ Reward	Management/ Operational	Full Mission Stimulator and Mini Bridge



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	4 true and relative vectors, graphic representation of target information and danger areas .5 deriving and analyzing information, critical echoes, exclusion areas and trial manoeuvres			12. Select sea-stabilized mode.			
C4 Use of ECDIS to maintain th safety of navigation	C4.1 Navigation Using ECDIS Knowledge of the capability and limitations of ECDIS operations, including:	At the end of the assessment the candidate must be able to use ECDIS to maintain safety of navigation	Monitors information on ECDIS in a manner that contributes to safe navigation				
	.1 a thorough understanding of Electronic Navigation Chart (ENC) data, data accuracy, presentation			Monitoring of at least three (3) types of information on ECDIS in a manner that contributes to safe navigation such as: a. standard display b. display base c. all other inf d. information such as spot			



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	rules, display option and other chart data formats			soundings, submarine cables and pipelines, ferry routes, details of all isolated dangers, details of aids to navigation, contents of cautionary notes, ENC edition date, geodetic datum, magnetic variation, graticule, place names			
	.2 the dangers of over-reliance			1. The limitations of ECDIS as a navigational tool; 2. potential risk of improper system functioning of the system; 3. system limitations, including those of its sensors; 4. hydrographic data inaccuracy, limitations of vector and raster electronic charts (ECDIS vs RCDS and ENC vs RNC); and 5. potential risk of human errors. Emphasis should be placed on the need to keep a proper lookout and to perform periodical			
				checking, especially of the ship's position, by ECDIS-independent methods.			



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	.3 familiarity with the functions of ECDIS required by performance standards in force		Knowledge of the limitations of the equipment and detection of misrepresentati on of information is essential for the safe use of ECDIS.	Emphasized during the assessment the following factors: a) performance standards of the equipment; b) radar data representation on an electric chart, elimination of discrepancy between the radar image and electronic chart; c) possible projection discrepancies between an electronic and paper charts; d) possible scale discrepancies between an electronic and paper charts; e) effects of using different reference systems for positioning; f) effects of using different horizontal and vertical datums; g) effects of motion of the ship in a seaway; h) ECDIS limitations in raster			



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				chart display mode;			
				i) potential errors in the display of:			
				1) the own ship's position			
				2) radar data and ARPA and AIS information			
				different geodetic coordinate systems;			
				j) verification of the results of manual or automatic data correction;			
				comparison of chart data and radar picture and			
				checking the own's ship's position by using the other independent position-fixing systems.			
	C4.2 Proficiency in operation, interpretation, and analysis of information obtained from	At the end of the assessment the candidate must be proficient in the operation, interpretation, and analysis of	Correctness of interpretation of the information obtained from ECDIS	Operate ECDIS where RADAR/ARPA, speed log, GPS, eco sounder, anemometer, gyro compass and VDRare connected: a) connect RADAR/ARPA to			



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	.1 use of functions that are integrated with other navigation systems in various installations, including proper functioning and adjustments to desired settings	information obtained from ECDIS		b) indicate target's speed vectors; c) indicate target's tracks; d) achieve target's tracks; e) view the table of the targets; f) check alignment of radar overlay with charted geographic features; g) simulate one or more manoeuvres; h) make corrections to own ship's position, using a reference point captured by ARPA; and i.) make corrections using the ARPA's cursor and electronic bar. Use of ECDIS by setting up and maintaining display: a) obtain the optimum display			



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				of ECDIS information; b) select display presentation (standard display, display base, all other information displayed individually on demand; c) adjust all variable radar/ARPA display controls for optimum display of data; d) select of convenient configuration; e) selectas appropriate, required speed input to ECDIS; f) select the timescale of vectors; and g) checks position, radar/ARPA, compass, speed input sensors and ECDIS			
	.2 safe monitoring and adjustment of information,		Monitoring of information obtained from ECDIS in a manner that	Use of ECDIS where AIS is connected: a) interface ECDIS with AIS; b) interpret AIS data;			



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	including own position, sea area display, mode and orientation, chart data displayed, route monitoring, user-created information layer, contacts (when interfaced with AIS and/or RADAR tracking) and RADAR overlay functions (when interfaced) 3. confirmation of vessel position by alternative means		contributes to safe navigation	c) indicate target's speed vectors; d) indicate target's tracks; and e) achieve target's tracks Use ECDIS by manual correction of ship's position and motion parameters: a) plot ship's position in deadreckoning mode (when the satellite and radio navigation system receiver is switched off)			



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				 b) plot ship's position, when automatically obtained coordinates are inaccurate; and 			
				c) course and speed values are obtained			
	.4 efficient use of setting to ensure			Interpret and react properly to at least four (4) of the following alarms:			
	conformance to operational procedures,			a) absence of the next chart in the ECDIS database;			
	including alarm parameters for			b) crossing a safety contour;			
	anti- grounding,			c) exceeding cross-track limits;			
	proximity to contacts and special areas,			d) deviation from planned route;			
	completeness of chart data			e) approaching a waypoint;			
	and chart update status,			f) approaching a critical point;			
	and backup arrangements			g) discrepancy between calculated and actual time of arrival to a waypoint;			
				h) information on under-scaling			



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				or over-scaling;			
				 i) approaching an isolated navigational danger or danger area; 			
				j) crossing a specified area;			
				k) selecting a different geodetic datum;			
				l) approaching other ships;			
				m) watch termination;			
				n) switching timer;			
				o) system test failure;			
				p) malfunctioning of the positioning system used in ECDIS;			
				q) failure of dead reckoning; and			
				r) inability to fix vessel's position using navigational system.			
	.5 adjustments of			Use of ECDIS by setting and			



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	setting and values to suit the present conditions			maintaining display: a) obtain the optimum display of ECDIS information using the correct starting procedure; b) select display presentation (standard display, display base, all other information displayed individually on demand); c) adjustall variable ECDIS display controls for optimum	Trocedure		
	.6 situational awareness using ECDIS			display controls for optimum display of data; d)select convenient configuration; e) select, as appropriate, the required speed input to ECDIS; Use of ECDIS by setting the detection and misrepresentation of			
	including safe water and proximity of hazards, set and drift, chart data and scale selection,			information and proper action taken to avoid any of the following errors: a) ignoring over scaling of the display;			



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	suitability of route, contact detection and management, and integrity of sensors			 b) uncritical acceptance of the own ship's position; c) confusion of display mode; d) confusion of chart scale; e) confusion of reference systems; 			
				f) different models of presentation; g) different modes of vector stabilization;			
			Safety of navigation is maintained through adjustments made to the ship's course and speed through ECDIS-controlled	h) differences between true north and gyro north (radar) i.) using the same data reference system; j) using the appropriate charts scale; k) using the best-suited sensor to the given situation and	Rubrics		
			track-keeping functions (when fitted)	circumstances I) entering the correct values of			



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					safety data; 1) the own ship's safety countour; 2) safety depth (safewater) and 3) events m) proper use of all available data			
C5	Respond to emergencies	5.1 Emergency Procedures .1 Precautions for the protections and safety of passengers in emergency situations		he MARINA C	f the candidate has suc Competency Assessmen		-	



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	.2 Initial action to be taken following a collision or a grounding; initial damage assessment and control	At the end of the assessment the candidate must be able to initial action to be taken following a collision or a grounding; initial damage assessment and control	Appropriateness of initial action in accordance with the urgency of situation and nature of emergency	Act appropriately based on the urgency of situation and nature of emergency such as: a) Collision 1. raise the alarm 2. inform the Master 3. establish contact with other vessel and exchange all relevant information 4. if possible, offer assistance to the other vessel 5. collect all facts about occurrence 6. make sure the logbook has been properly kept 7. do not erase any information on the working chart (times, positions, courses steered, logs, etc.) 8. ensure that the movement book is properly kept in ink 9. collect the course recorder printout and the printouts from	Penalty/ Reward	Management/ Operational	Full Mission Stimulator And Mini Bridge



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
				telegraph recorders and the engine room 10. take particularly note of the exact time of the collision, the heading of the vessel at the time of the collision, the angle of blow by or to the other vessel, the speed of each vessel at the time of the collision, any alteration of speed and course prior to the collision 11. Update if necessary, vessel's position in radio room, satellite terminal and other automatic distress transmitters (GMDSS) 12. Sound bilges and tanks 13. Notify other vessels in the vicinity if required b) Grounding; 1. Stop engines immediately			



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
				 Inform the Master Sound general alarm Watertight doors to be closed VHF watch maintained on channel 16 Broadcast to other vessels Sound signals, Light / Shapes to be exhibited especially important in case of fog) Deck lighting switched on Check position on chart Take note of any valuable information (time, course steered, speed, log, eventual manoeuvres, etc.) Sound bilges, tanks Immediately take overboard soundings around vessel to check on what type of sandbank the ship is lying 			



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
				c) Initial damage assessment; 1. Inform Master 2. Reduce speed 3. Exhibit "Not under command" shapes or lights 4. Use minimum rudder angle 5. Manoeuvre ship according to the weather and external situation 6. Update vessel's position in radio room, satellite terminal and other automatic distress transmitters (GMDSS) 7. Check reason of the loss of stability 8. Sound bilges and tanks 9. Consider distress call 10. Consider abandon ship 11. Duly enter all decisions actions			



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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
		.3 Appreciation of the procedures for rescuing persons from the sea, assisting a ship in distress, responding to emergencies in port	At the end of the assessment the candidate must be able to appreciate procedures for rescuing persons from the sea, assisting a ship in distress, responding to emergencies in port	Appropriateness of the procedures for rescuing persons from the sea, assisting a ship in distress, responding to emergencies that arise in port	taken in logbook. d) Control of damage in case of heavy weather 1. Record position 2. Nature of damage 3. Sound tanks and bilges 4. Check damage to cargo 5. Check course and speed Describes procedure for rescuing persons from the sea Describe procedure for assisting a ship in distress Describe procedure for responding to emergencies in port	Penalty/ Reward	Management/ Operational	Full Mission Stimulator And Mini Bridge
C 6	Respond to distress signal at sea	C6.1 Search and Rescue .1 Knowledge of the			by successfully passing Operational Level Com			



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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
		contents of the International Aeronautical and Maritime Search and Rescue (IAMSAR) Manual	Rescue Radio Aeronautical an		cations including p earch and Rescue (IAI	rocedure MSAR) Ma		nternational
C7	Use the IMO Standard Marine Communicatio n Phrases and use English in written and oral form	C7.1 English Language .1 Adequate knowledge of the English language to enable the officer to use charts and other nautical publications, to understand meteorological information and messages concerning ship's safety and operation, to communicate with other ships, coast stations and VTS centres	examination in t	he MARINA	the candidate has su Competency Assessme mmunication Phrases a	ent System	Competen	ice 7 – Use

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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
C8	Transmit and receive	and to perform the officer's duties also with a multilingual crew, including the ability to use and understand the IMO Standard Maritime Communication Phrases (IMO SMCP) C8.1 Visual Signaling	At the end of the assessment the	Success of communication	Communicate successfully within the operator's area of	Penalty / Reward	Operational/ Functional	Full Mission Stimulator and
	information by visual signaling	.1 Ability to use the International Code of Signals .2 Ability to transmit and receive, by Morse light, light signal SOS as specified in Annex IV of the International Regulations for Preventing Collisions at Sea,	candidate must be able transmit and receive information by visual signaling	within the operator's area of responsibility is consistent	responsibility by sending at least 3 of the following SOS signal specified in Annex IV of the COLREG's, 1972 as amended such as: a. a rocket parachute flare b. International Code Signal N.C. c. flames on the vessel d. a smoke signal giving off orange-coloured smoke e. Raising and lowering arms outstretched to			Mini Bridge



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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
С9	Maneuver the ship	1971, as amended, and appendix 1 of the International Code of Signals, and visual signaling of single letter signals as also specified in the International Code of Signals C9.1 Ship Maneuvering and Handling 1. Knowledge of the effects of deadweight, draught, trim, speed and under-keel clearance on turning circles and stopping distances	At the end of the assessment the candidate must have the knowledge of the effects of deadweight, draught, trim, speed and under-keel clearance on turning circles and stopping distances	Determination of the effects of deadweight, draught, trim, speed and under-keel clearance on turning circles and stopping distances	each side f. SOS signal in the Morse Light Determines how changes in the following will affect the ship's maneuvering characteristics: 1. deadweight 2. draught 3. trim 4. speed 5. under-keel clearance on turning circles 6. stopping distances (to develop scenarios for deep water and shallow water, two for each (depth zones can be used);	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and Mini Bridge
		2. Knowledge of the effects of	At the end of the assessment the	Proper adjustment is	Perform the following:	Reward/ Penalty	Operational/ Functional	Full Mission Stimulator and



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	wind and current on ship handling	candidate must have the knowledge of the effects of wind and current on ship handling	made to the ships course and speed	 Execute at turn to port or starboard by more than 45° from the original heading by applying a minimum of 5 degrees and a maximum of 15 degrees of rudder Ease off rudder as the ship approaches the new course; and Maintain on the new course without overshooting the course by more than 5 degrees. Adjust speed as necessary 			Mini Bridge
	3. Knowledge of maneuvers and procedures for the rescue of person overboard	At the end of the assessment the candidate will have a knowledge of maneuvers and procedures for the rescue of person overboard	Immediate initiation of an appropriate man over board procedure	Perform Williamson Turn or Anderson Turn (as appropriate in the following sequence): 1. Order full rudder to the side of the Man overboard; 2. Sound Man over board signal if other vessels are in sight; a) Simulate releasing the MOB buoy; b) Mark the ship's position			



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Ó	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
					on ARPA/GPS /ECDIS; c) Simulate a "Mayday" call on VHF notifying any vessels in vicinity of the Man overboard; d) Complete the recovery turn; e) State that the rescue boat would be prepared for launching; and f) Reduce the speed and stop the vessel when on the reciprocal course, and within 0.1 nm of the MOB to begin the recovery/search.			
		4. Knowledge of squat, shallow-water and similar effects	At the end of the assessment the candidate will have a knowledge on squat, shallow-water and similar effects	Proper adjustment is made to the ships course and speed	Perform ship's maneuver by considering the effects of the following: a) deadweight; b) draft; c) trim; d) speed; e) under-keel clearance on turning circle and stopping distance; f) wind and current; and g) squat and shallow water			
		5. Knowledge of	At the end of the	Conformance to	Perform proper procedures for			



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	the procedures for anchoring and mooring	assessment the candidate will have a knowledge on the procedures for anchoring and mooring	the proper procedure on anchoring and mooring	anchoring and mooring considering the following: A. Planning Determine the: 1. depth of water; 2. type of bottom; 3. wind and current; 4. bottom obstructions; 5. room to swing; 6. place to anchor; 7. courses and maneuver to the anchor site; and 8. desired final heading; B. Approach Ensure that the ship does not pass to windward or up current of any anchored vessel or hazard to navigation. C. Placement 1. slow approach is made to anchor site; 2. ship's position is checked by natural landmarks and aids forming ranges ahead and abeam; 3. vessel is stopped when			



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
Competence	KUP			in position on the approximate desired final heading; and 4. anchor is correctly dropped for the depth of water D. Laying out: 1. The ship is backed slowly; and 2. A length of chain 5 to 7 times the water depth is paid out slowly. E. Fetching up: 1. The ship is allowed to fetch up on the chain; and The ship rides on a final heading that is within 40° of the desired final heading			



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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
FUNT	TION 2	CARGO HANDLING A	ND STOWAGE AT THE	OPERATIONAL L	EVEL			
C10	Monitor the loading, stowage, securing, care during the voyage and the unloading of cargoes	C10.1 Cargo handling, stowage and securing .1 Knowledge of the effect of cargo, including heavy lifts, on the seaworthiness and stability of the ship	At the end of the assessment, the candidate must be able to monitor loading of cargo within the acceptable longitudinal stress of the vessel.	Achievement of cargo operations in accordance with the cargo plans or other documents and established safety rules/regulations , equipment operating instructions and shipboard stowage limitations	Monitor cargo operation to conform with the approved loading sequence as follows: 1. Load cargo in Hold no.4, pump out WBT and TST 6&7 P/S and after peak tank; 2. Load cargo in Hold no. 2 pump out DB ballast and topside Tk 2&3 P/S and FPT; 3. Load cargo in Hold no.3 to full; and 4. Load cargo in Hold no.4 to complete the loading operation. Monitor the cargo operations to ensure that the stability criteria are within the acceptable limits: 1. Mean draft between 9.25 to 9.55 meters to meet the accepted stability and international grain code; 2. Grain heeling moment 7300 - 12690 T*M; 3. Heel Angle for grain 4.74 – 5.59 degrees	Checklist	Operational/ Functional	Automatic Data Based Equipment



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	.2 Knowledge of	At the end of the	Compliance of	4. Angle of Deck Edge Immersion (DEI); 17.68 – 18.55 degrees 5. Go not less than 0.15 meter; and 6. Trim not more than 1 meter by astern Monitor cargo operations to			
	safe handling, stowage and securing of cargoes, including dangerous, hazardous and	assessment, the candidate must have the Knowledge of safe handling, stowage and securing of cargoes, including dangerous, hazardous	the handling of dangerous, hazardous and harmful cargoes with the international regulations and recognized standards and codes of safe practice	ensure compliance with international regulations and recognized standards and codes of safe working practice such as: 1. the vessel shall be provided with an approved Grain Loading Manual; 2. the vessel must be provided with Grain Loading Certificate issued by Classification Society; 3. the vessel must have an approved loading plan; and 4. the vessel must have an approved grain loading calculation form.			
	.3 ability to establish and maintain effective communication	At the end of the assessment the candidate must have the ability to establish	Effectiveness of communication	Ensure clear and consistent communications between ship to shore during cargo operations such as:			

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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
		during loading and unloading	and maintain effective communication during loading and unloading		 filling up ship – shore checklist; establishing close communication with loading master using portable radio at designated channel; and establishing close communication with the cargo officer throughout the operations 			
C11	Inspect and report defects and damage to cargo spaces, hatch covers and ballast tanks	C11.1 Knowledge and ability to explain where to look for damage and defects most commonly encountered .1 loading and unloading operations .2 corrosion .3 severe weather conditions C11.2 Ability to state which parts of the ship shall be inspected each	theoretical exa	amination in – Inspect a	nstrated if the candida n the MARINA Cor and report defects and	mpetency	Assessmer	nt System



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Competence	КИР	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	time in order to cover all parts within a given period of time		'				'
	C11.3 Identify those elements of the ship structure which are critical to the safety of the ship						
	C11.4 State the causes of corrosion in cargo spaces and ballast tanks and how corrosion can be identified and prevented						
	C11.5 Knowledge of procedure on how the inspections shall be carried out						
	C11.6 Ability to explain how to ensure reliable detection of defects and damages						



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
Competence	C11.7 Understanding the purpose of the "enhanced survey programme"	Outcome	Criteria	Performance Standard	Procedure	Simulation	Assessment



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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment		
FUNT	TION 3	CONTROLLING THE	OPERATION OF THE SH	IP AND CARE FO	R PERSONS ON BOARD AT THE	OPERATION A	L LEVEL			
C12	Ensure compliance with pollution prevention requirements	C12.1 Prevention of pollution of the marine environment and anti- pollution procedures								
		.1 Knowledge of the precautions to be taken to prevent pollution of the marine environment	theoretical exa	is Competence is demonstrated if the candidate has successfully pass coretical examination in the MARINA Competency Assessment suppetence 12 - Ensure compliance with pollution prevention requirements.						
		.2 Anti-pollution procedures and all associated equipment								
		.3 Importance of proactive measures to protect the marine environment								
C13	Maintain	C13.1	This Competen	ce is demor	nstrated if the candidat	te has su	ccessfully	passed the		



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
seaworthiness of the ship	Ship stability .1 Working knowledge and application of stability, trim and stress tables, diagrams and stress-calculating equipment .2 Understanding of fundamental actions to be taken in the event of partial loss of intact buoyancy .3 Understanding of the fundamentals of watertight integrity C13.2 Ship Construction	Competence '	13 – Maintain s	the MARINA (seaworthiness of the the the Automatic Data-b	e ship and the	Practical A	-



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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
		.1 General knowledge of the principal structural members of a ship and the proper names for the various parts						
C14	Prevent, control and fight fires on board	C14.1 Fire prevention and fire-fighting appliances .1 Ability to organize fire drills .2 Knowledge of classes and chemistry of fire .3 Knowledge of fire-fighting systems .4 Knowledge of action to be taken in the	This Competend Training IMO Mo		strated if the candidate	e has succ	essfully cor	npleted the



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Ó	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
		event of fire, including fires involving oil systems						'
C15	Operate life- saving appliances	C15.1 Life-saving .1 Ability to organize abandon ship drills and knowledge of the operation of survival craft and rescue boats, their launching appliances and arrangements, and their equipment, including radio life-saving appliances, satellite EPIRBs, SARTs, immersion suits and thermal protective aids	This Competend Training IMO Mo		strated if the candidate	has succ	essfully cor	npleted the
C16	Apply medical first aid on	C16.1 Medical Aid						

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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	board ship	.1 Practical application of medical guides and advice by radio, including the ability to take effective action based on such knowledge in the case of accidents or illnesses that are likely to occur on board ship	This Competend Training IMO Mo		strated if the candidate	has succ	essfully con	npleted the
C17	Monitor compliance with legislative requirements	C17.1 Basic working knowledge of the relevant IMO conventions concerning safety of life at sea, security and protection of the marine environment	theoretical exa	amination ir	nstrated if the candidate the MARINA Community mpliance with legislative	npetency	Assessmer	
C18	Application of leadership and team working skills	C18.1 Working knowledge of shipboard personnel management and training	At the end of the assessment the candidate must have a working knowledge of shipboard personnel management and	Descriptions of the basic duties and responsibilities of vessel personnel.	Describes the duties and responsibilities of the following: 1. Master; 2. Deck department including: a) Chief Mate;	Rubrics	Management/ Operational	Full Mission Simulator

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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
		training		b) Second Mate; c) Third Mate; d) Bosun e) Able Seamen;			
	C18.2 A knowledge of related international maritime conventions and recommendations, and national legislation	At the end of assessment, the candidate must be able to describe the basic international maritime conventions and national regulations	Descriptions of the basic international maritime conventions and national regulations	 Describes the following: International Convention for the Safety of Life at Sea (SOLAS); International Ship and Port Facility Security Code (ISPS); International Safety Management Code (ISM); 4. International Convention on Standards of Training, Certification and Watchkeeping for Seafarers 1978, as amended (STCW); MARPOL 73/78 and its Annexes; Oil Pollution Act of 1990 (OPA 90) and; Onboard contracts, including POEA/CBA labor contracts. 	Rubrics	Management/ Operational	Full Mission Simulator
	C18.3 Ability to apply task and workload management, including:	At the end of assessment, the candidate must be able to perform the duties of an OIC-NW	Performance of the duties of an OIC-NW	Perform the following duties: 1. Preparation and scheduling the order of events in anticipation of	Rubrics	Operational/M anagement	Full Mission Stimulator and Mini Bridge



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	 .1 Planning and coordination .2 Personnel management .3 Time and resource constraints .4 Prioritization 			the pilot boarding; 2. Check and relay helm orders as per Master's direction; 3. Using signal devices (flags, signal lights, radio communications, etc.) as directed by the Master; and 4. Delegating and calling out personnel so that equipment is safely rigged and/or unrigged as needed.			
	C18.4 Knowledge and ability to apply effective resource management: .1 Allocation, assignment and prioritization of resources .2 Effective communication on-board and ashore	At the end of assessment, the candidate must be able to supervise the ship's operations under the direction of the department head.	Supervision of various ship's operations under the direction of the department head.	Supervise the following duties under the direction of the department head: 1. Reviewing the work plan with the Chief Mate or Master; 2. Checking equipment to ensure operational readiness; 3. Tool box meeting with assigned crewmembers. 4. Delegating tasks to each of the assigned crewmembers 5. Establishing and maintaining	Rubrics	Operational/M anagement	Full Mission Stimulator and Mini Bridge



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	 .3 Decisions reflect consideration of team experiences .4 Assertiveness and leadership, including motivation .5 Obtaining and maintaining situational awareness 			communications with bridge, team and shore personnel; 6. Showing situational awareness around the vessel including potential hazards that each team member may encounter; and 7. Actively managing the assigned crewmembers motivating them to work safely and efficiently while anticipating and mitigating any hazards.			
	C18.5 Knowledge and ability to apply decision-making requirements: .1 Situation and risk assessment .2 Identify and consider generated options .3 Selecting course of action	At the end of assessment, the candidate must be able to supervise a fire or emergency team under the supervision of the team leader	Supervision of fire or emergency team under the supervision of the squad leader	Supervise the following duties under the direction of the team leader: 1. Briefs the team on the situation, the approach, and the procedures to be executed; 2. Assigns task to each crew members, briefing them about any special procedures or events that may concern them; 3. Verifies the assigned crewmembers to ensure that they are using personal protective equipment (PPE)	Rubrics	Operational/M anagement	Full Mission Stimulator and Mini Bridge

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	Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
		.4 Evaluation of outcome effectiveness			correctly and appropriately; 4. Verifies the assigned crewmembers to ensure that they have brought the assigned equipment as per Muster list; 5. Executes the contingency plan to handle the emergency situation; and 6. Participates in de-briefing, presents the positive results, feedbacks 7. and makes recommendations to improve procedures			
C19	Contribute to the safety of personnel and ship	C19.1 Knowledge of personal survival techniques	under Marina C	Circular 2013	the candidate has suc 3-11 Annex III Refresho Prevention and Fire Fig	er Trainin	•	•



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Competence	KUP	Assessment Outcome	Performance Criteria	Performance Standard	Scoring Procedure	Level of Simulation	Methods of Assessment
	C19.3 Knowledge of elementary first aid	This KUP is den Course 1.14 – M		the candidate has succe	essfully cor	mpleted the	IMO Model
	C19.4 Knowledge of personal safety and social responsibilities		rcular 2013-1	the candidate has suc 1 Annex IV Updating Tr	•	•	•